

# Weak Lensing Goes Flexion

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# Outline

## 1 Flexion

- Introduction
- How we measure flexion
- Estimate flexion parameters

## 2 Numerical tests

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## Observation



Galaxy Cluster Abell 370  
(VLT UT1 + FORS1)

ESO PR Photo 47c/98 (26 November 1998)

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## Introduction

# What is flexion ?

- Small scale variation in weak lensing
- Higher order lensing effect
- Gradient of shear

## Introduction

## 2nd-order expansion of lens equation

- Second-order

$$\beta_i = \theta_i - \psi_{,ij}\theta_j - \psi_{,ijk}\theta_j\theta_k/2$$

- Differential operators

$$\nabla_c := \frac{\partial}{\partial \theta_1} + i \frac{\partial}{\partial \theta_2}, \quad \nabla_c^* := \frac{\partial}{\partial \theta_1} - i \frac{\partial}{\partial \theta_2}$$

The differential operator  $\nabla_c$  turns a spin-n field into a spin-(n+1) field, whereas  $\nabla_c^*$  works opposite. For example,  $\nabla_c^* \gamma = \nabla_c \kappa$  found by Kaiser (1995).

- then lens equation reads

$$\beta = (1 - \kappa)\theta - \gamma\theta^* - \frac{1}{4}\nabla_c^* \kappa \theta^2 - \frac{1}{2}\nabla_c \kappa \theta \theta^* - \frac{1}{4}\nabla_c \gamma (\theta^*)^2$$

## Introduction

# Mass sheet Degeneracy!

- Under the transformation of  $\kappa_\lambda = (1 - \lambda) + \lambda\kappa$ , the observable shape of the gravitational lens systems doesn't change. The shear is unobservable, but the **reduced shear** can be measured:

$$g = \frac{\gamma}{1 - \kappa}$$

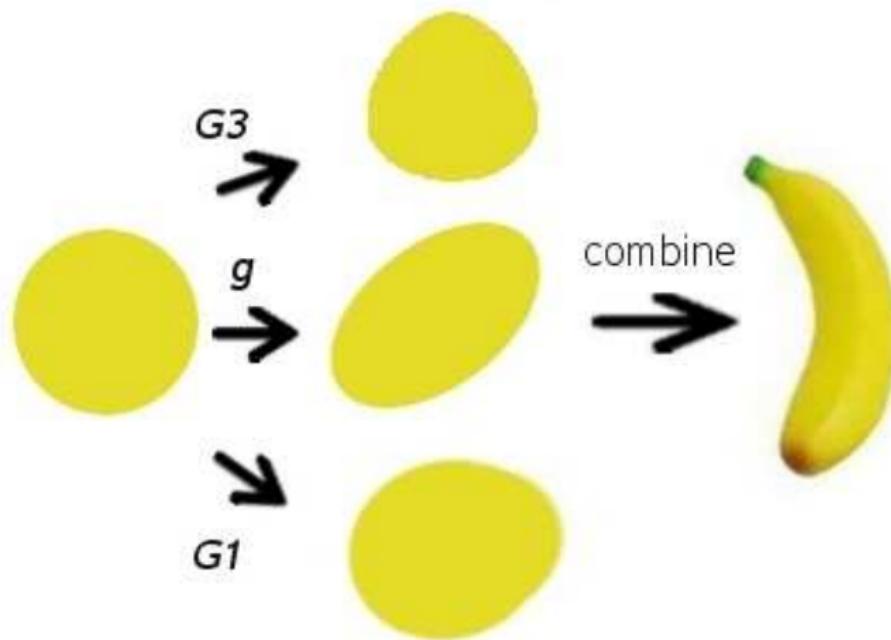
- Then reduced  $\beta$

$$\hat{\beta} \equiv \frac{\beta}{(1 - \kappa)} = \theta - g\theta^* - \Psi_1^*(G_1)\theta^2 - 2\Psi_1\theta\theta^* - \Psi_3(G_1, G_3)(\theta^*)^2$$

where  $G_3 = \nabla_c g$ ,  $G_1 = \nabla_c^* g$  are **reduced flexion** parameters.

- The lensing equation determined by 3 parameters  $g$ ,  $G_1$  and  $G_3$ .

# Weak lensing goes Bananas



How we measure flexion

# Measurements

- How to measure? Which observable characterize flexion

## Definition

- Shapelets (Refregier, 2003);
- Brightness Moments

$$Mom[f(\beta)] = \int d^2\beta f(\beta) I^s(\beta), \quad (\text{Okura et al, 2006 HLCs})$$

We follow this, but in the reduced flexion.

How we measure flexion

# Brightness Moments

- 2nd-order Brightness Moments

$$Q_2 = \frac{1}{S} \int d^2\theta \theta^2 I(\theta), \quad Q_0 = \frac{1}{S} \int d^2\theta \theta \theta^* I(\theta),$$

with  $S$  is the total flux, and origin defined by  $\int d^2\theta \theta I(\theta) = 0$ .

- then comes to 3rd-order,...

$$T_3 \equiv \frac{1}{S} \int d^2\theta \theta^3 I(\theta); \quad T_1 \equiv \frac{1}{S} \int d^2\theta \theta^2 \theta^* I(\theta).$$

How we measure flexion

# Moments equation

- By expanding brightness moments of source using lensing equation and determinant, we get relation between source and image moments.

$$Q_2^s = Q_2 - 2gQ_0 + g^2 Q_2^* + A\mathcal{G} - (B\mathcal{G})^2$$

$$\mathcal{T}^s = \tau + C\mathcal{G}$$

A,B are column matrices, C is matrix composed of moments, and  $\mathcal{G}^T = (G_3^*, G_1^*, G_1, G_3)$ ,  
 $\mathcal{T}^{s,T} = (T_3^{s*}, T_1^{s*}, T_1^s, T_3^s)$ ,  $\tau = \tau(T_1, T_3, g)$ .

Estimate flexion parameters

# Weak approximate

- In the weak lensing case ( $g \ll 1$ ), one can remove some terms, and simplify the brightness moments relation

$$\begin{pmatrix} T_1^s \\ Q_2^s \\ T_3^s \end{pmatrix} = \begin{pmatrix} T_1 \\ Q_2 \\ T_3 \end{pmatrix} + \begin{pmatrix} \frac{12Q_0^2 - 9F_0}{4} & 0 & 0 \\ 0 & -2Q_0 & 0 \\ 0 & 0 & -\frac{3}{4}F_0 \end{pmatrix} \begin{pmatrix} G_1 \\ g \\ G_3 \end{pmatrix}$$



Estimate flexion parameters

## Source assumption

Same as in weak lensing, assuming that the source ellipticity and orientation are random,  $\langle Q_2^s \rangle = 0$ ,  $\langle T_1^s \rangle = 0$  and  $\langle T_3^s \rangle = 0$

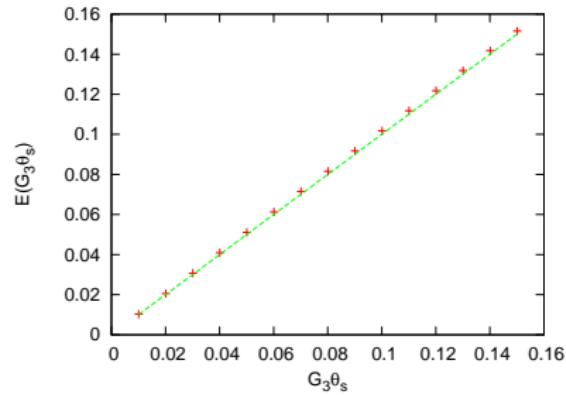
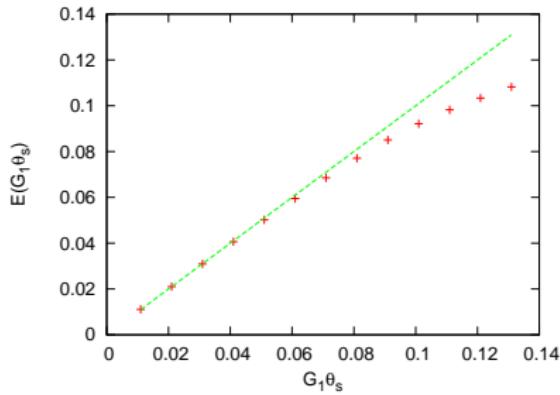
- $G_1$  and  $G_3$  Estimators

$$G_1 = \frac{4}{9F_0 - 12Q_0^2} T_1$$

$$G_3 = \frac{4}{3F_0} T_3$$

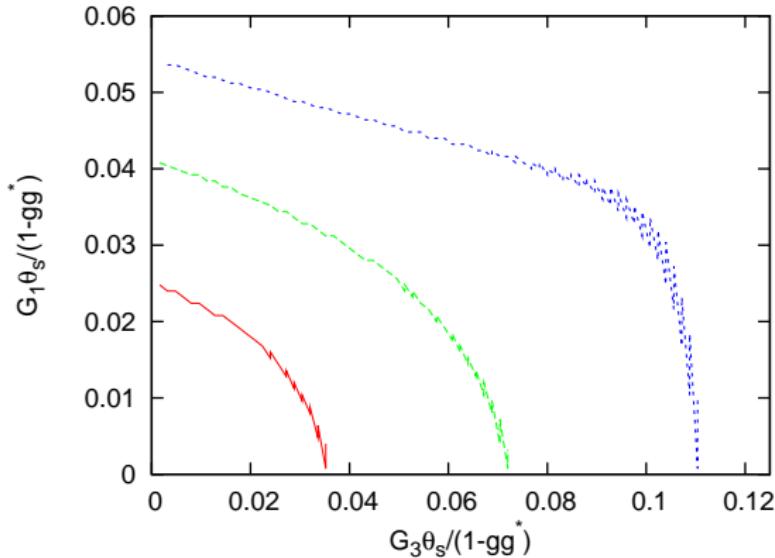
# Simulation

- Mean value of the estimators, over a source population with Gaussian ellipticity distribution,  $g = 0.01$ .
- The accuracy only depends on the product  $G_i\theta_s$  ( $i = 1, 3$ ).



# Error contours

- 5,10,15 percent errors on  $g$  for  $g = 0.05$



# Multiple solutions and Critical curves

- Non-linear lensing equation

$$\hat{\beta} = \theta - g\theta^* - \Psi_1^*(G_1)\theta^2 - 2\Psi_1\theta\theta^* - \Psi_3(G_1, G_3)(\theta^*)^2$$

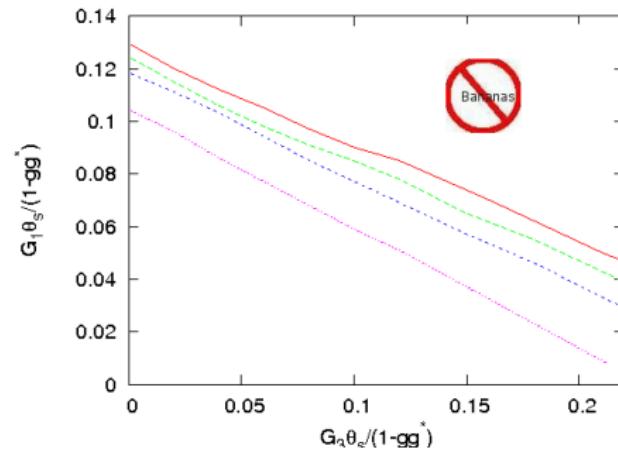
More than one solutions of the equation is allowed.



- Critical curves come in !!

# Critical curves Limit

- Limits of valid flexion estimator



# Summary

- Flexion is the gradient of shear and is simply related to the higher-order brightness moments.
- Only reduced shear and reduced flexion are measurable.
- Estimator bias is small, and depends on the dimensionless quantities  $G_1\theta_s$ ,  $G_3\theta_s$  and  $g$ .
- Flexion estimators have a limit by critical curves
- Future application  
Galaxy-galaxy lensing  
Substructure clusters